

# Linear Bandits

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# Outline

## 1 Recap

## 2 Linear Bandits

- Setting
- LinUCB
- An Optimal Regret Bound

## 3 Analysis

- Regret Analysis
- Confidence Analysis

# Generalization in RL

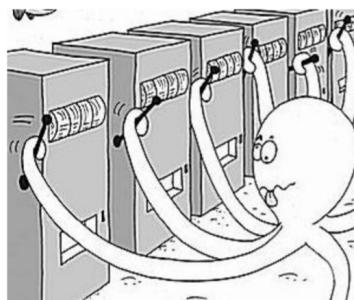
r

- (distribution free) Agnostic learning is not possible in RL:  
we showed that to get  $O(\log |\Pi|)$  sample complexity we need either:
  - $\text{poly}(|\mathcal{S}|)$  samples OR
  - ~~$\text{poly}(H)$~~  samples.  
*EXPCHT*in order to learn the best policy in some policy class.
- upshot: we need stronger assumptions for RL analysis.

# Multi-Armed-Bandits: High-level picture

## Setting

- Set of alternatives (arms)
- Each arm has a reward distribution
- Learner adaptively selects arms
- Challenge: Distributions not known



Images from:

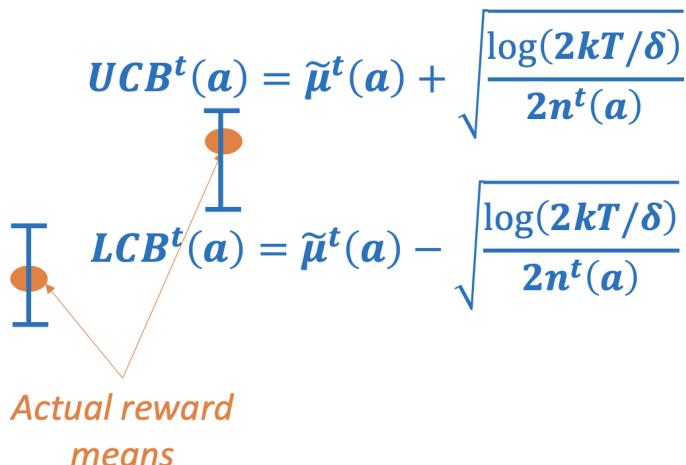
<https://towardsdatascience.com/beyond-a-b-testing-multi-armed-bandit-experiments-1493f709f804>  
<https://www.aqusagtechnologies.com/wp-content/uploads/2017/04/Online-advertising.jpeg>

# Upper Confidence Bound (UCB)

Pick arm with highest **Upper Confidence Bound**

By Hoeffding and union bound, with probability  $\geq 1 - \delta$ , it holds  $\forall a \in [k], t \in [T]$ :

$$\mu(a) \in [LCB^t(a), UCB^t(a)]$$



**Claim :** In the event that all confidence intervals hold, the regret is at most  $\sum_t (UCB^t(a^t) - LCB^t(a^t)) + \delta \cdot T$

Proof:  $Reg^t = \mu(a^*) - \mu(a^t)$

$$\leq UCB^t(a^*) - LCB^t(a^t)$$
$$\leq UCB^t(a^t) - LCB^t(a^t)$$

# Upper Confidence Bound (UCB)

$$UCB^t(a) = \tilde{\mu}^t(a) + \sqrt{\frac{\log(2kT/\delta)}{2n^t(a)}}$$

$$LCB^t(a) = \tilde{\mu}^t(a) - \sqrt{\frac{\log(2kT/\delta)}{2n^t(a)}}$$

Claim : In the event that all confidence intervals hold, the regret is at most  $\sum_t (UCB^t(a^t) - LCB^t(a^t)) + \delta \cdot T$

## Regret bound by confidence sum

$$\begin{aligned} \sum_t (UCB^t(a^t) - LCB^t(a^t)) &\leq 2 \cdot \sum_t \sqrt{\frac{\log\left(\frac{2kT}{\delta}\right)}{2n^t(a^t)}} = \sum_a \sum_{j=1}^{N(a)} \sqrt{\frac{\log\left(\frac{2kT}{\delta}\right)}{2 \cdot j}} \quad \text{Request} \\ &\leq \sum_a \sum_{j=1}^{\frac{T}{k}} \sqrt{\frac{\log\left(\frac{2kT}{\delta}\right)}{2 \cdot j}} \leq k \cdot \sqrt{\log\left(\frac{2kT}{\delta}\right) \cdot \frac{T}{k}} = O\left(\sqrt{T \cdot k \cdot \log\left(\frac{kT}{\delta}\right)}\right) \end{aligned}$$

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# Handling Large Actions Spaces

Lin Bandit Model  
Abej Long 1999

- On each round, we must choose a decision  $x_t \in D \subset \mathbb{R}^d$ .

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- Obtain a reward  $r_t \in [-1, 1]$ , where

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# Handling Large Actions Spaces

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$$\mathbb{E}[r_t | x_t = x] = \mu^* \cdot x \in [-1, 1],$$

- so the conditional expectation of  $r_t$  is linear)
- Also, we have the *noise sequence*,

$$\eta_t = r_t - \mu^* \cdot x_t$$

is i.i.d noise.

observe

$$r_t = \mu^* \cdot x + \eta$$

↑  
Unknown

# Our Objective

$$\sum_{t=0}^{T-1} r_t \approx \sum_{t=0}^{T-1} \mu^* \cdot x_t$$

If  $x_0, \dots, x_{T-1}$  are our decisions, then our cumulative regret is

$$R_T = \sum_{t=0}^{T-1} \mu^* \cdot x_t - \underbrace{\sum_{t=0}^{T-1} \mu^* \cdot x^*}_{\text{online Lin. Programming}}$$

where  $x^* \in D$  is an optimal decision for  $\mu^*$ , i.e.

$$x^* \in \operatorname{argmax}_{x \in D} \mu^* \cdot x$$

If  $D$   
was a polytope-

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# The “Confidence Ball”

After  $t$  rounds, define our uncertainty region  $\text{BALL}_t$ : with center,  $\hat{\mu}_t$ , and shape,  $\Sigma_t$ , using the  $\lambda$ -regularized least squares solution:

$$\hat{\mu}_t = \arg \min_{\mu} \sum_{\tau=0}^{t-1} \|\mu \cdot x_{\underline{\tau}} - r_{\underline{\tau}}\|_2^2 + \lambda \|\mu\|_2^2$$

$$= \Sigma_t^{-1} \sum_{\tau=0}^{t-1} r_{\tau} x_{\tau},$$

$$\Sigma_t = \lambda I + \sum_{\tau=0}^{t-1} x_{\underline{\tau}} x_{\underline{\tau}}^\top, \text{ with } \Sigma_0 = \lambda I.$$

seen

$x_1 \dots x_{t-1}$   
 $r_1 \dots r_{t-1}$

# The “Confidence Ball”

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$$\begin{aligned}\hat{\mu}_t &= \arg \min_{\mu} \sum_{\tau=0}^{t-1} \|\mu \cdot x_t - r_t\|_2^2 + \lambda \|\mu\|_2^2 \\ &= \Sigma_t^{-1} \sum_{\tau=0}^{t-1} r_\tau x_\tau, \\ \Sigma_t &= \lambda I + \sum_{\tau=0}^{t-1} x_t x_t^\top, \text{ with } \Sigma_0 = \lambda I.\end{aligned}$$

Define the uncertainty region:

$$\text{BALL}_t = \left\{ (\hat{\mu}_t - \mu^*)^\top \Sigma_t^{-1} (\hat{\mu}_t - \mu^*) \leq \beta_t \right\},$$

where  $\beta_t$  is a parameter of the algorithm.

# LinUCB (the algo)

- 1 Input:  $\lambda, \beta_t$
- 2 For  $t = 0, 1, \dots$ 
  - 1 Execute

$$x_t = \operatorname{argmax}_{x \in D} \max_{w \in \text{BALL}_t} w \cdot x$$

and observe the reward  $r_t$ .

- 2 Update  $\text{BALL}_{t+1}$ .

using  $x_t, r_t$

# LinUCB Regret Bound

Sublinear regret:  $R_T \leq O^*(d\sqrt{T})$

poly dependence on  $d$ , no dependence on the cardinality  $|D|$ .

$$|D| \approx \left(\frac{1}{\epsilon}\right)^d$$

# LinUCB Regret Bound

Sublinear regret:  $R_T \leq O^*(d\sqrt{T})$

poly dependence on  $d$ , no dependence on the cardinality  $|D|$ .

wlog  $\exists$  scaling  $W = O(\sqrt{d})$   
 $\|x\| \leq 1$

## Theorem

Suppose: bounded noise  $|\eta_t| \leq \sigma$ , that  $\|\mu^*\| \leq W$ , and that  $\|x\| \leq B$  for all  $x \in D$ . Set  $\lambda = \sigma^2/W^2$  and

$$\beta_t := \sigma^2 \left( 2 + 4d \log \left( 1 + \frac{\cancel{t} TB^2 W^2}{d} \right) + 8 \log(4/\delta) \right).$$

With probability greater than  $1 - \delta$ , that for all  $t \geq 0$ ,

$$R_T \leq c\sigma\sqrt{T} \left( d \log \left( 1 + \frac{TB^2 W^2}{d\sigma^2} \right) + \log(4/\delta) \right)$$

Tight  
in  
 $d$  &  $T$

where  $c$  is an absolute constant.

(due to Dani, K., and Hayes '09)

av reg.  $\cancel{d/\sqrt{T}}$

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# Confidence

In establishing the upper bounds there are two main propositions from which the upper bounds follow. The first is in showing that the confidence region is valid.

## Proposition

*(Confidence) Let  $\delta > 0$ . We have that*

$$\Pr(\forall t, \mu^* \in \text{BALL}_t) \geq 1 - \delta.$$

# Sum of Squares Regret Bound

Assuming the confidence event holds, the following controls on the growth of the regret.

## Proposition

(Sum of Squares Regret Bound) Define:

$$\text{regret}_t = \mu^* \cdot x^* - \mu^* \cdot x_t$$

↙ instantaneous  
regret

Suppose  $\|x\| \leq B$  for  $x \in D$ . Suppose  $\beta_t$  is set as in Theorem 1.

Suppose  $\mu^* \in \text{BALL}_t$  for all  $t$ , then

$O(\sqrt{\log T})$

$$\sum_{t=0}^{T-1} \text{regret}_t^2 \leq 4\beta_T d \log \left( 1 + \frac{TB^2}{d\lambda} \right)$$

# Completing the Proof

$$\beta_T \approx O(d\log T)$$

**Proof:** [Proof of Theorem 1] With the two previous Propositions, along with the Cauchy-Schwarz inequality, we have, with probability at least  $1 - \delta$ ,

$$R_T = \sum_{t=0}^{T-1} \text{regret}_t \leq \left( T \sum_{t=0}^{T-1} \text{regret}_t^2 \right)^{1/2} \leq \sqrt{4T\beta_T d \log \left( 1 + \frac{TB^2}{d\lambda} \right)}.$$

The remainder of the proof follows from using our chosen value of  $\beta_T$  and algebraic manipulations. ■

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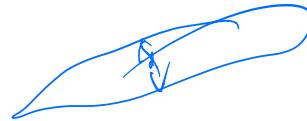
# “Width” of Confidence Ball

## Lemma

Let  $x \in D$ . If  $\mu \in \text{BALL}_t$  and  $x \in D$ . Then

$$|(\mu - \hat{\mu}_t)^\top x| \leq \sqrt{\beta_t x^\top \Sigma_t^{-1} x}$$

# “Width” of Confidence Ball



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$$|(\mu - \hat{\mu}_t)^\top x| \leq \sqrt{\beta_t x^\top \Sigma_t^{-1} x}$$

**Proof:** By Cauchy-Schwarz, we have:

$$\begin{aligned} |(\mu - \hat{\mu}_t)^\top x| &= |(\mu - \hat{\mu}_t)^\top \Sigma_t^{1/2} \Sigma_t^{-1/2} x| = |(\Sigma_t^{1/2}(\mu - \hat{\mu}_t))^\top \Sigma_t^{-1/2} x| \\ &\leq \|\Sigma_t^{1/2}(\mu - \hat{\mu}_t)\| \|\Sigma_t^{-1/2} x\| = \|\Sigma_t^{1/2}(\mu - \hat{\mu}_t)\| \sqrt{x^\top \Sigma_t^{-1} x} \leq \sqrt{\beta_t x^\top \Sigma_t^{-1} x} \end{aligned}$$

where the last inequality holds since  $\mu \in \text{BALL}_t$ . ■

# Instantaneous Regret Lemma

Define

$$w_t := \sqrt{x_t^\top \Sigma_t^{-1} x_t}$$

which is the “normalized width” at time  $t$  in the direction of our decision.

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Lemma

Fix  $t \leq T$ . If  $\mu^* \in \text{BALL}_t$ , then

$$\text{regret}_t \leq 2 \min(\sqrt{\beta_t} w_t, 1) \leq 2\sqrt{\beta_T} \min(w_t, 1)$$

$\beta_t$  is increasing

# Instantaneous Regret Lemma

Define

$$w_t := \sqrt{x_t^\top \Sigma_t^{-1} x_t}$$

$$\Sigma_t \triangleq \Sigma_\epsilon + x_t x_t^\top$$

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Lemma

Fix  $t \leq T$ . If  $\mu^* \in \text{BALL}_t$ , then

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**Proof:** Let  $\tilde{\mu} \in \text{BALL}_t$  denote the vector which minimizes the dot product  $\tilde{\mu}^\top x_t$ . By choice of  $x_t$ , we have

$$\tilde{\mu}^\top x_t = \max_{\mu \in \text{BALL}_t} \max_{x \in D} \mu^\top x \geq (\mu^*)^\top x^*,$$

where the inequality used the hypothesis  $\mu^* \in \text{BALL}_t$ . Hence,

$$\begin{aligned} \text{regret}_t &= (\mu^*)^\top x^* - (\mu^*)^\top x_t \leq (\tilde{\mu} - \mu^*)^\top x_t \\ &= (\tilde{\mu} - \hat{\mu}_t)^\top x_t + (\hat{\mu}_t - \mu^*)^\top x_t \leq 2\sqrt{\beta_t} w_t \end{aligned}$$

# Geometric Argument: Part 1

The next two lemmas give us 'geometric' potential function argument, where we can bound the sum of widths independently of the choices made by the algorithm.

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## Lemma

We have:

$$\det \Sigma_T = \det \Sigma_0 \prod_{t=0}^{T-1} (1 + w_t^2).$$

# Geometric Argument: Part 1

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$$w_t = \sqrt{x_t \sum_{\ell} x_\ell}$$

## Lemma

We have:

$$\det \Sigma_T = \det \Sigma_0 \prod_{t=0}^{T-1} (1 + w_t^2).$$

Volume update  
Equality

**Proof:** By the definition of  $\Sigma_{t+1}$ , we have

$$\begin{aligned} \det \Sigma_{t+1} &= \det(\Sigma_t + x_t x_t^\top) = \det(\Sigma_t^{1/2} (I + \Sigma_t^{-1/2} x_t x_t^\top \Sigma_t^{-1/2}) \Sigma_t^{1/2}) \\ &= \det(\Sigma_t) \det(I + \Sigma_t^{-1/2} x_t (\Sigma_t^{-1/2} x_t)^\top) = \det(\Sigma_t) \det(I + v_t v_t^\top), \end{aligned}$$

where  $v_t := \Sigma_t^{-1/2} x_t$ . Now observe that  $v_t^\top v_t = w_t^2$  and ...

■

# Geometric Argument: Part 2

## Lemma

For any sequence  $x_0, \dots, x_{T-1}$  such that, for  $t < T$ ,  $\|x_t\|_2 \leq B$ , we have:

$$\Sigma_0 \trianglelefteq \Sigma_T$$
$$\log \left( \det \Sigma_{T-1} / \det \Sigma_0 \right) = \log \det \left( I + \frac{1}{\lambda} \sum_{t=0}^{T-1} x_t x_t^\top \right) \leq d \log \left( 1 + \frac{TB^2}{d\lambda} \right).$$

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**Proof:** Denote the eigenvalues of  $\sum_{t=0}^{T-1} x_t x_t^\top$  as  $\sigma_1, \dots, \sigma_d$ , and note:

$$\sum_{i=1}^d \sigma_i = \text{Trace} \left( \sum_{t=0}^{T-1} x_t x_t^\top \right) = \sum_{t=0}^{T-1} \|x_t\|^2 \leq TB^2.$$

Using the AM-GM inequality,

$$\begin{aligned} \log \det \left( I + \frac{1}{\lambda} \sum_{t=0}^{T-1} x_t x_t^\top \right) &= \log \left( \prod_{i=1}^d (1 + \sigma_i/\lambda) \right) \\ &= d \log \left( \prod_{i=1}^d (1 + \sigma_i/\lambda) \right)^{1/d} \leq d \log \left( \frac{1}{d} \sum_{i=1}^d (1 + \sigma_i/\lambda) \right) \leq d \log \left( 1 + \frac{TB^2}{d\lambda} \right) \end{aligned}$$

# Proving “sum of squares regret” Proposition

**Proof:** [Proof of Proposition 3] Assume  $\mu^* \in \text{BALL}_t$  for all  $t$ . We have:

$$\begin{aligned} \sum_{t=0}^{T-1} \text{regret}_t^2 &\leq \sum_{t=0}^{T-1} 4\beta_t \min(w_t^2, 1) \leq 4\beta_T \sum_{t=0}^{T-1} \min(w_t^2, 1) \\ &\leq 4\beta_T \sum_{t=0}^{T-1} \ln(1 + w_t^2) \leq 4\beta_T \log \left( \det \Sigma_{T-1} / \det \Sigma_0 \right) \\ &= 4\beta_T d \log \left( 1 + \frac{TB^2}{d\lambda} \right) \end{aligned}$$

where the first inequality follows from Lemma 5; the second from that  $\beta_t$  is an increasing function of  $t$ ; the third uses that for  $0 \leq y \leq 1$ ,  $\ln(1 + y) \geq y/2$ ; the final two inequalities follow by Lemmas 6 and 7. ■

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$$\Pr(\forall t, \mu^* \in \text{Ball}(\epsilon)) \leq S$$

# Confidence [Proof of Proposition 2]

**Proof:** Since  $r_\tau = \mathbf{x}_\tau \cdot \mu^* + \eta_\tau$ , we have:

$$\begin{aligned}\hat{\mu}_t - \mu^* &= \Sigma_t^{-1} \sum_{\tau=0}^{t-1} r_\tau \mathbf{x}_\tau - \mu^* = \Sigma_t^{-1} \sum_{\tau=0}^{t-1} \mathbf{x}_\tau (\mathbf{x}_\tau \cdot \mu^* + \eta_\tau) - \mu^* \\ &= \Sigma_t^{-1} \left( \sum_{\tau=0}^{t-1} \mathbf{x}_\tau (\mathbf{x}_\tau)^\top \right) \mu^* - \mu^* + \Sigma_t^{-1} \sum_{\tau=0}^{t-1} \eta_\tau \mathbf{x}_\tau \\ &= \lambda \Sigma_t^{-1} \mu^* + \Sigma_t^{-1} \sum_{\tau=0}^{t-1} \eta_\tau \mathbf{x}_\tau\end{aligned}$$

$\Sigma_t = \sum \mathbf{x}_\tau \mathbf{x}_\tau^\top \succ \mathbb{I}$

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Σ<sub>x</sub> λ/2

By the triangle inequality,

$$\begin{aligned}(\hat{\mu}_t - \mu^*)^\top \Sigma_t^{-1} (\hat{\mu}_t - \mu^*) &\leq \left\| \lambda (\Sigma_t)^{-1/2} \mu^* \right\| + \left\| \Sigma_t^{-1} \sum_{\tau=0}^{t-1} \eta_\tau \mathbf{x}_\tau \right\| \\ &\leq \sqrt{\lambda} \|\mu^*\| + ??.\end{aligned}$$

How can we bound “??” To be continued... ■

# Self-Normalizing Sum

$$\varepsilon_i \xrightarrow{\text{exp}} M_i \quad V_t \xrightarrow{\text{exp}} S_t$$

## Lemma (Self-Normalized Bound for Vector-Valued Martingales)

(Abassi et. al '11) Suppose  $\{\varepsilon_i\}_{i=1}^{\infty}$  are mean zero random variables (can be generalized to martingales), and  $\varepsilon_i$  is bounded by  $\sigma$ . Let  $\{X_i\}_{i=1}^{\infty}$  be a stochastic process. Define  $V_t = V_0 + \sum_{i=1}^t X_i X_i^\top$ . With probability at least  $1 - \delta$ , we have for all  $t \geq 1$ :

$$\left\| \sum_{i=1}^t X_i \varepsilon_i \right\|_{V_t^{-1}}^2 \leq 2\sigma^2 \log \left( \frac{\det(V_t)^{1/2} \det(V_0)^{-1/2}}{\delta} \right).$$

# Continued... [Proof of Proposition 2]

**Proof:**

$$\begin{aligned} (\hat{\mu}_t - \mu^*)^\top \Sigma_t^{-1} (\hat{\mu}_t - \mu^*) &\leq \left\| \lambda(\Sigma_t)^{-1/2} \mu^* \right\| + \left\| \Sigma_t^{-1} \sum_{\tau=0}^{t-1} \eta_\tau x_\tau \right\| \\ &\leq \sqrt{\lambda} \|\mu^*\| + \sqrt{2\sigma^2 \log (\det(\Sigma_t) \det(\Sigma^0)^{-1} / \delta_t)}. \end{aligned}$$

We seek to lower bound  $\Pr(\forall t, \mu^* \in \text{BALL}_t)$ . Assign failure probability  $\delta_t = (3/\pi^2)/t^2$  for the  $t$ -th event, which gives us:

$$\begin{aligned} 1 - \Pr(\forall t, \mu^* \in \text{BALL}_t) &= \Pr(\exists t, \mu^* \notin \text{BALL}_t) \leq \sum_{t=1}^{\infty} \Pr(\mu^* \notin \text{BALL}_t) \\ &< \sum_{t=1}^{\infty} (1/t^2)(3/\pi^2) = 1/2. \end{aligned}$$

This along with Lemma 7 completes the proof. ■