Generalization in Large scale MDPs

Sham Kakade and Wen Sun

CS 6789: Foundations of Reinforcement Learning

Recap: Bellman error of Q

We define **average** Bellman error of a Q-estimate g below:

$$\mathscr{E}(g; f, h) = \mathbb{E}_{s_h, a_h \sim d_h^{\pi_f}} \left[g(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P(\cdot|s_h, a_h)} \left[\max_{a \in \mathscr{A}} g(s_{h+1}, a) \right] \right]$$

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We know that $\mathscr{E}(Q^\star; f, h) = 0, \forall f$

Recap: Bellman error of the associated V functions

We can define **average** Bellman error wrt the V-function induced by g as well:

$$\mathscr{E}(g; f, h) = \mathbb{E}_{s_h \sim d_h^{\pi_f}} \left[V_g(s_h) - r(s_h, \pi_g(s_h)) - \mathbb{E}_{s_{h+1} \sim P(\cdot|s_h, \pi_g(s_h))} \left[V_g(s_{h+1}) \right] \right]$$

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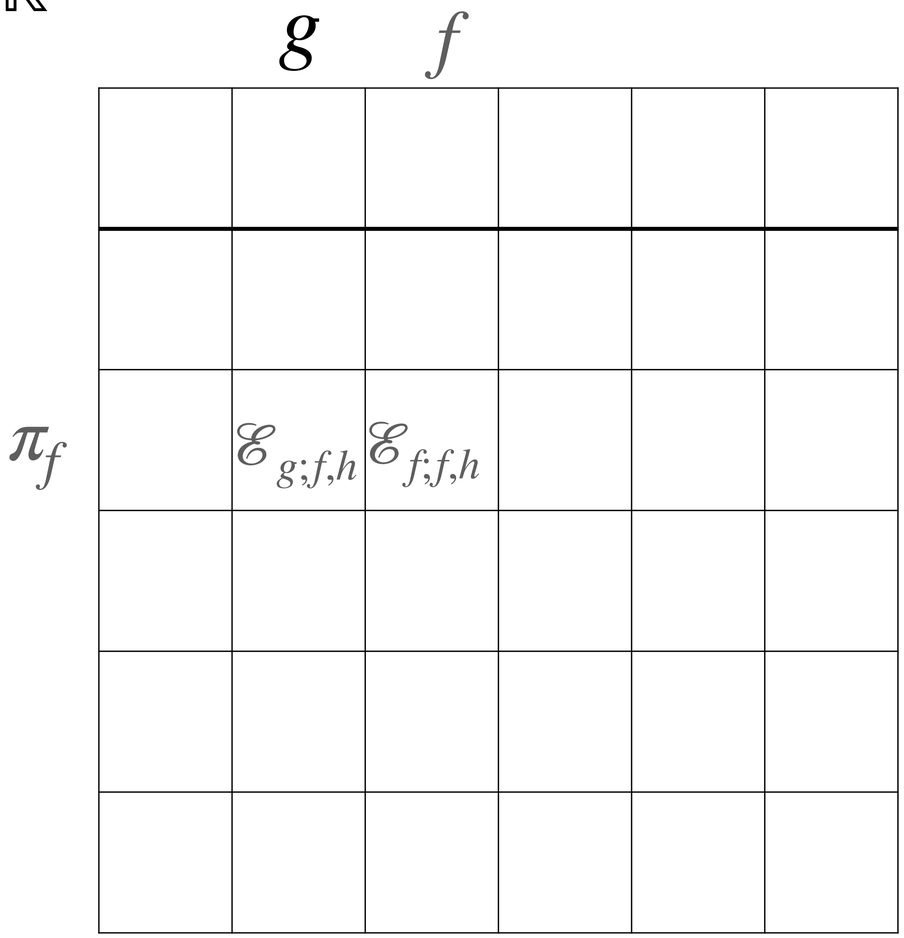
Again we have $\mathscr{E}(Q^\star; f, h) = 0, \forall f$

(because: $V_{Q^\star}(s) - r(s, \pi_{Q^\star}(s)) - \mathbb{E}_{s' \sim P_h(.|s, \pi_{Q^\star}(s))} V_{Q^\star}(s') = 0$)

Recap: The Q / V-Bellman rank

$\forall h : \mathscr{E}_h \in \mathbb{R}^{|\mathscr{F}| \times |\mathscr{F}|}$



Rank of this Matrix is defined as Bellman Rank

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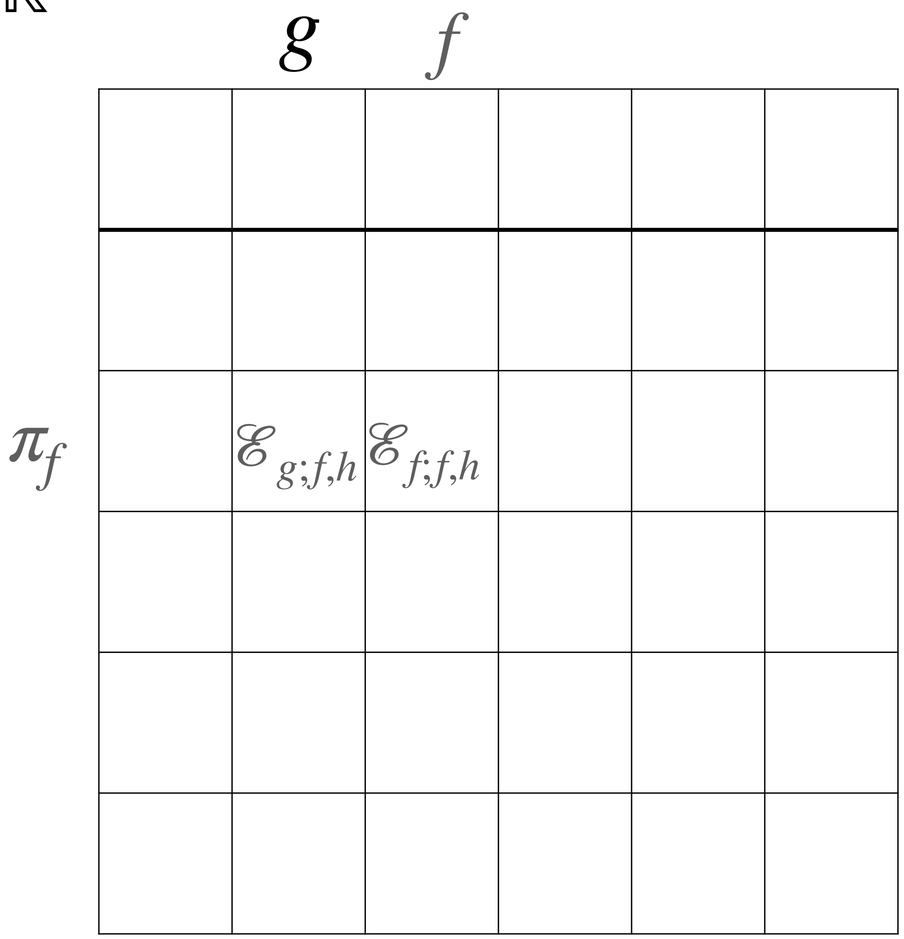

There are two mappings

$W_h : \mathscr{F} \mapsto \mathbb{R}^d, \quad X_h : \mathscr{F} \mapsto \mathbb{R}^d$

(d = Q/V Bellman-rank)

$\forall f, g \in \mathscr{F} : \mathscr{E}(g; f, h) = \langle W_h(g), X_h(f) \rangle$

Rank of this Matrix is defined as Bellman Rank

Recap: Many examples have low Bellman rank

1. Linear Bellman completion (including linear and tabular MDPs, and LQR)

2. Linear $Q^\star$ & $V^\star$ (captures the $Q^\star$-state abstraction)

3. Low-rank MDPs (unknown representation that needs to be learned)

4. Many others: Reactive POMDPs, Contextual bandit, Low-occupancy measures…

Question for Today

Can we design a universal algorithm that learns efficiently for MDPs w/ low-Q/V Bellman rank?

e.g., poly(H, b-rank, $\ln(|\mathscr{H}|), 1/\epsilon^2$)

Outline for Today

1. The Bilinear-UCB algorithm (BLin-UCB)

2. Theoretical Guarantee and analysis of BLin-UCB

For Q-Bellman rank case:

Recall our hypothesis class $\mathcal{F}$, where each $g \in \mathcal{F}$ is in the form of $g(s, a)$

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If we had a dataset $\mathcal{D} := \{s_h, a_h, s_{h+1}\}$ where $s_h, a_h \sim d_h^{\pi_f}, s_{h+1} \sim P_h(\cdot \mid s_h, a_h)$

$\forall g : \mathbb{E}_{\mathcal{D}}[\ell(s_h, a_h, s_{h+1}, g)]$ is an unbiased est of $\mathcal{E}(g; f, h)$

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The Algorithm:

At iteration t :

Select $f_t = \arg\max_{g \in \mathcal{F}} V_g(s_0)$

s.t., $\forall h : \sum_{i=0}^{t-1} \left(\mathbb{E}_{\mathcal{D}_{h,i}}[\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2$

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Intuition behind the algorithm:

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3. Optimism allows explore and exploit tradeoff!

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w/ probability at least $1 - \delta$,

$$\forall g : \left| \mathbb{E}_{\nu} \ell(s, a, s', g) - \mathbb{E}_{\mathscr{D}} \ell(s, a, s', g) \right| \leq \varepsilon_{gen}(m, \mathscr{F}, \delta)$$

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Example: when $\mathscr{F}$ is discrete (for B-rank loss), Hoeffding + union bound over $\mathscr{F}$ implies:

$$\varepsilon_{gen}(m, \mathscr{F}, \delta) := 2H \sqrt{\frac{\ln(|\mathscr{F}|/\delta)}{m}}$$

Analysis of BLin-UCB

After running BLin-UCB for $T = \widetilde{O}\left(Hd\right)$ many iterations, there exists a policy among T many policies, such that:

$$V^{\star}(s_0) - V^{\pi}(s_0) \leq \widetilde{O}\left(\varepsilon_{gen}\left(m, \mathscr{F}, \delta/(TH)\right) \cdot \sqrt{dH^3}\right)$$

(# of trajectories used: mHT)

Analysis of BLin-UCB

Example: discrete (but large) hypothesis class $\mathcal{F}$ for Q-Bellman rank

W/ prob $1-\delta$, BLin-UCB learns a policy with $V^{\star} - V^{\pi} \leq \epsilon$, w/ # of trajectories:

$$\widetilde{O}\left(\frac{H^6 d^2 \ln\left(|\mathcal{F}|/\delta\right)}{\epsilon^2}\right)$$

Analysis of BLin-UCB

Step 1: proving optimism via showing $f^\star$ is always a feasible solution (whp)

Recall constraint: $\forall h : \sum_{i=0}^{t-1} \left(\mathbb{E}_{\mathscr{D}_{h,i}}[\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2$

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$$(\mathbb{E}_{\mathscr{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f^\star))^2 \leq 2 \left(\mathbb{E}_{\mathscr{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f^\star) - \mathscr{E}(f^\star; f_i, h) \right)^2 + 2(\mathscr{E}(f^\star; f_i, h))^2$$

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$$\sum_{i=0}^{t-1} \left(\mathbb{E}_{\mathscr{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f^\star) \right)^2 \leq t\varepsilon_{gen}^2 \leq T\varepsilon_{gen}^2 := R^2$$

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Proof:

Recall the objective function:

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Analysis of BLin-UCB

Step 2: Using optimism to upper bound per-episode regret:

$$\text{Optimism} \Rightarrow V^{\star}(s_0) - V^{\pi_{f_t}}(s_0) \leq V_{f_t}(s_0) - V^{\pi_{f_t}}(s_0)$$

Lemma:

$$V_{f_t}(s_0) - V^{\pi_{f_t}}(s_0) = \sum_{h=0}^{H-1} \mathbb{E}_{s_h, a_h \sim d_h^{\pi_{f_t}}} \left[f_t(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P_h(s_h, a_h)} \max_{a'} f_t(s_{h+1}, a') \right]$$

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$$= \sum_{h=0}^{H-1} \mathscr{E}(f_t; f_t, h) = \sum_{h=0}^{H-1} W_h(f_t)^{\top} X_h(f_t)$$

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Key trick: telescoping

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Lemma:

$$V_{f_t}(s_0) - V^{\pi_{f_t}}(s_0) = \sum_{h=0}^{H-1} \mathbb{E}_{s_h, a_h \sim d_h^{\pi_{f_t}}} \left[f_t(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P_h(s_h, a_h)} \max_{a'} f_t(s_{h+1}, a') \right]$$

Key trick: telescoping

$$h = 0: \quad f_t(s_0, a_0) - \mathbb{E}_{s_1 \sim d_1^{\pi_{f_t}}} \max_{a'} f_t(s_1, a')$$

Analysis of BLin-UCB

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$$h = 2, \ldots$$

Analysis of BLin-UCB

Step 2: Using optimism to upper bound per-episode regret:

$$V^{\star}(s_0) - V^{\pi_{f_t}}(s_0) = \sum_{h=0}^{H-1} \mathbb{E}_{s_h, a_h \sim d_h^{\pi_{f_t}}} \left[f_t(s_h, a_h) - r(s_h, a_h) - \mathbb{E}_{s_{h+1} \sim P_h(s_h, a_h)} \max_{a'} f_t(s_{h+1}, a') \right]$$

$$= \sum_{h=0}^{H-1} \mathscr{E}(f_t; f_t, h) = \sum_{h=0}^{H-1} W_h(f_t)^{\top} X_h(f_t)$$

Define ``feature" covariance matrix $\Sigma_{t,h} = \sum_{i=0}^{t-1} X_h(f_i) X_h(f_i)^{\top} + \lambda I$

Via CS inequality:

$$V^{\star}(s_0) - V^{\pi_{f_t}}(s_0) \leq \sum_{h=0}^{H-1} \left\| W_h(f_t) \right\|_{\Sigma_{t,h}} \| X_h(f_t) \|_{\Sigma_{t,h}^{-1}}$$

Analysis of BLin-UCB

Summary so far, after optimism + per-episode regret decomposition, we get:

Define ``feature" covariance matrix $\Sigma_{t,h} = \sum_{i=0}^{t-1} X_h(f_i) X_h(f_i)^\top + \lambda I$

$$\forall t: \; V^\star(s_0) - V^{\pi_{f_t}}(s_0) \leq \sum_{h=0}^{H-1} \left\| W_h(f_t) \right\|_{\Sigma_{t,h}} \|X_h(f_t)\|_{\Sigma_{t,h}^{-1}}$$

Analysis of BLin-UCB

Step 3: argue that we make progress whenever π_{f_t} is not good…

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Recall constraint for f_t : $\quad \forall h : \sum_{i=0}^{t-1} \left(\mathbb{E}_{\mathscr{D}_{h,i}}[\ell(s_h, a_h, s_{h+1}, g)] \right)^2 \leq R^2 := T\varepsilon_{gen}^2$

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$$\Rightarrow \forall h : \sum_{i=0}^{t-1} \mathscr{E}(f_t; f_i, h)^2 \leq \sum_{i=0}^{t-1} 2 \left(\mathscr{E}(f_t; f_i, h) - \mathbb{E}_{\mathscr{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f_t) \right)^2 + \sum_{i=0}^{t-1} 2 \left(\mathbb{E}_{\mathscr{D}_{i,h}} \ell(s_h, a_h, s_{h+1}, f_t) \right)^2$$

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$$\Rightarrow \forall h : \sum_{i=0}^{t-1} \mathscr{E}(f_t; f_i, h)^2 \leq 4T\varepsilon_{gen}^2$$

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$$\Rightarrow \forall h : \left\| W_h(f_t) \right\|_{\Sigma_{t,h}}^2 \leq 4T\varepsilon_{gen}^2 + \lambda B_W^2$$

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If $V^\star(s_0) - V^{\pi_{f_t}}(s_0) \geq \epsilon$,

Then, we know that $\exists h$, such that $\|X_h(f_t)\|_{\Sigma_{t,h}^{-1}} \geq \epsilon / \sqrt{4T\varepsilon_{gen}^2 + \lambda B_W^2}$

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Which means that this new vector $X_h(f_t)$ is ``different" from previous ``data" $X_h(f_0), \ldots, X_h(f_{t-1})$

i.e., we explore a bit in a d dim space…

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(We will complete the proof in HW)

Summary for today

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1. The BLin-UCB algorithm:

Optimism driven; analysis uses the standard linear bandit style analysis

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Optimism driven; analysis uses the standard linear bandit style analysis

2. The BLin-UCB has poly sample complexity wrt B-rank

It means that this algorithm works for tabular MDPs, linear bandits, linear Bellman-completion, LQRs, Linear $Q^\star$ & $V^\star$, Low-rank MDP, latent variable MDPs, reactive POMDPs, etc

Starting from Thursday:

RL & Optimization:

How to do gradient ascent in RL?
Can gradient ascent find global optimality, despite RL usually has non-convex objective functions?