

Exploration in Tabular MDPs

Sham Kakade and Wen Sun

CS 6789: Foundations of Reinforcement Learning

Announcements

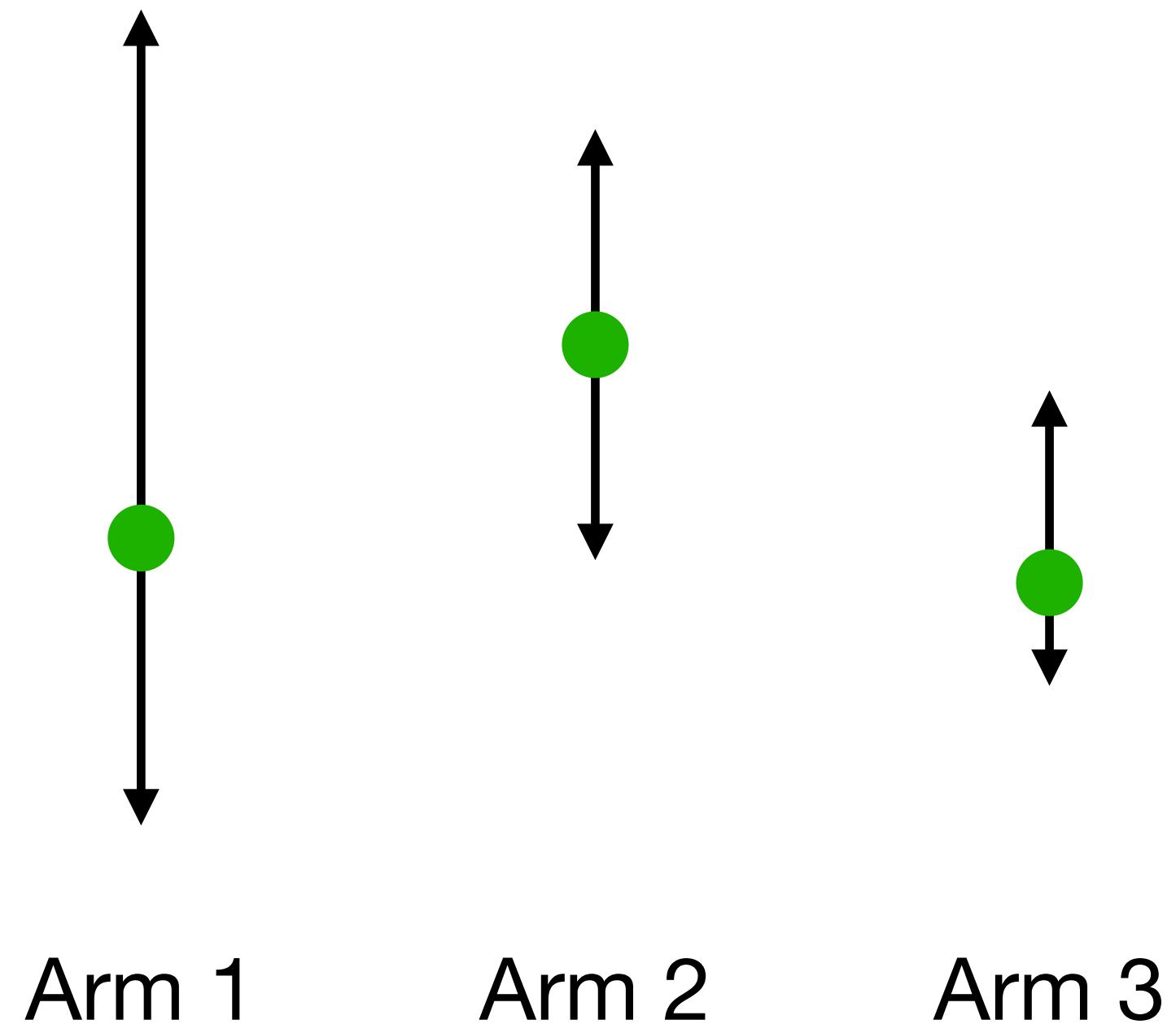
Course Project Website

<https://wensun.github.io/CS6789projects.html>

(Please start thinking about potential projects and feel free to discuss
w/ me and TA during office hours)

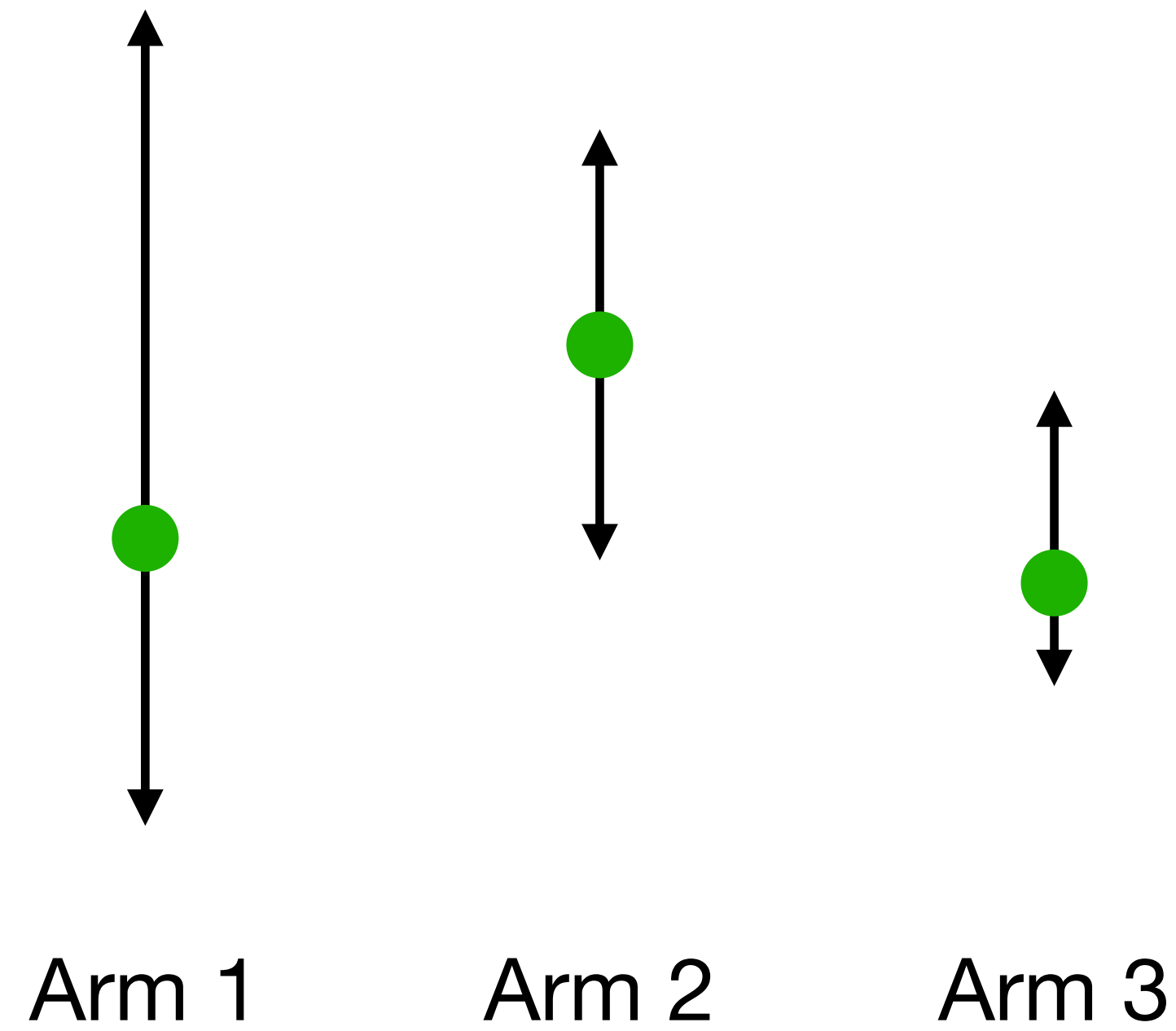
Recap:

Multi-armed Bandits and UCB Algorithm



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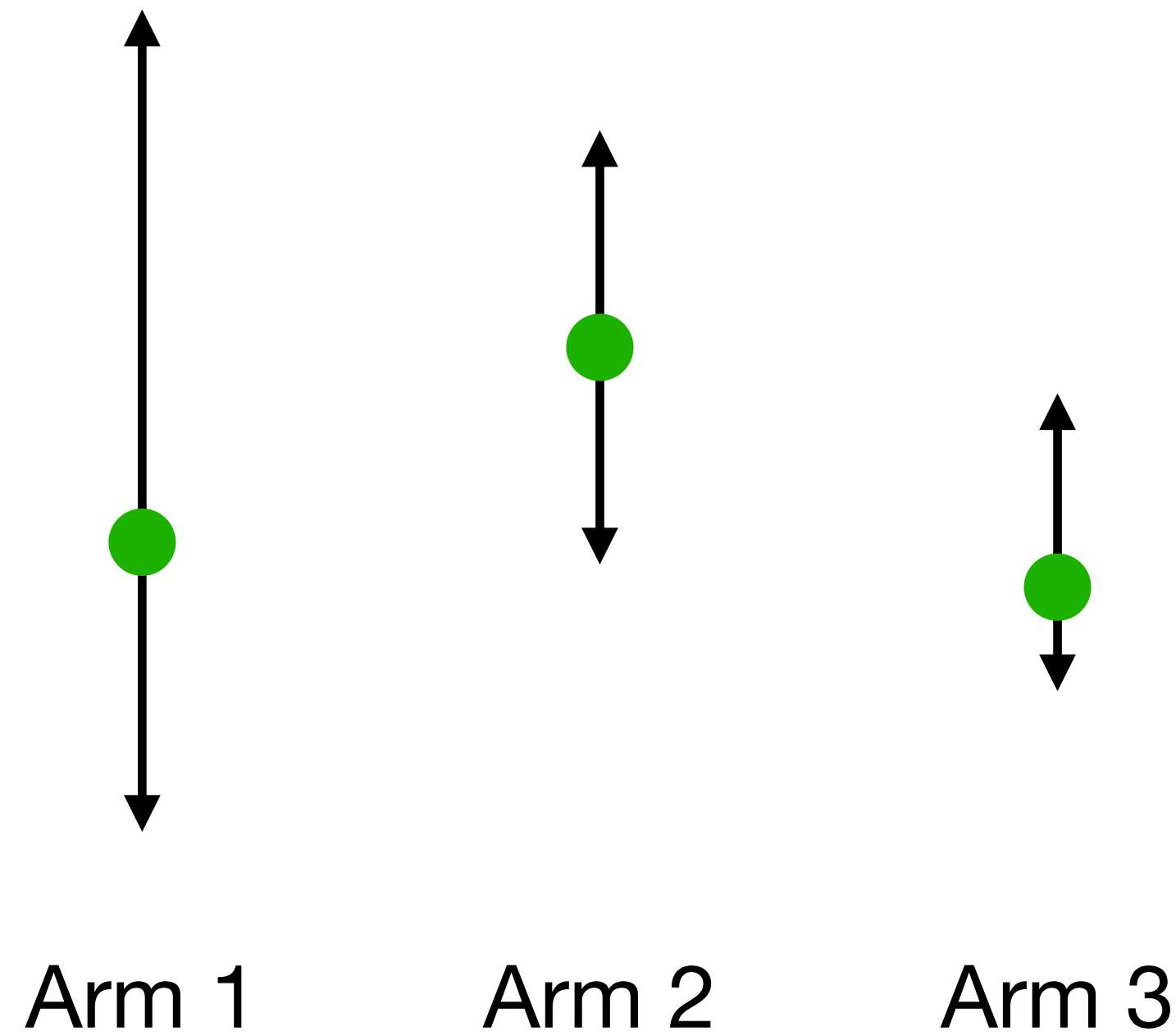
Multi-armed Bandits and UCB Algorithm



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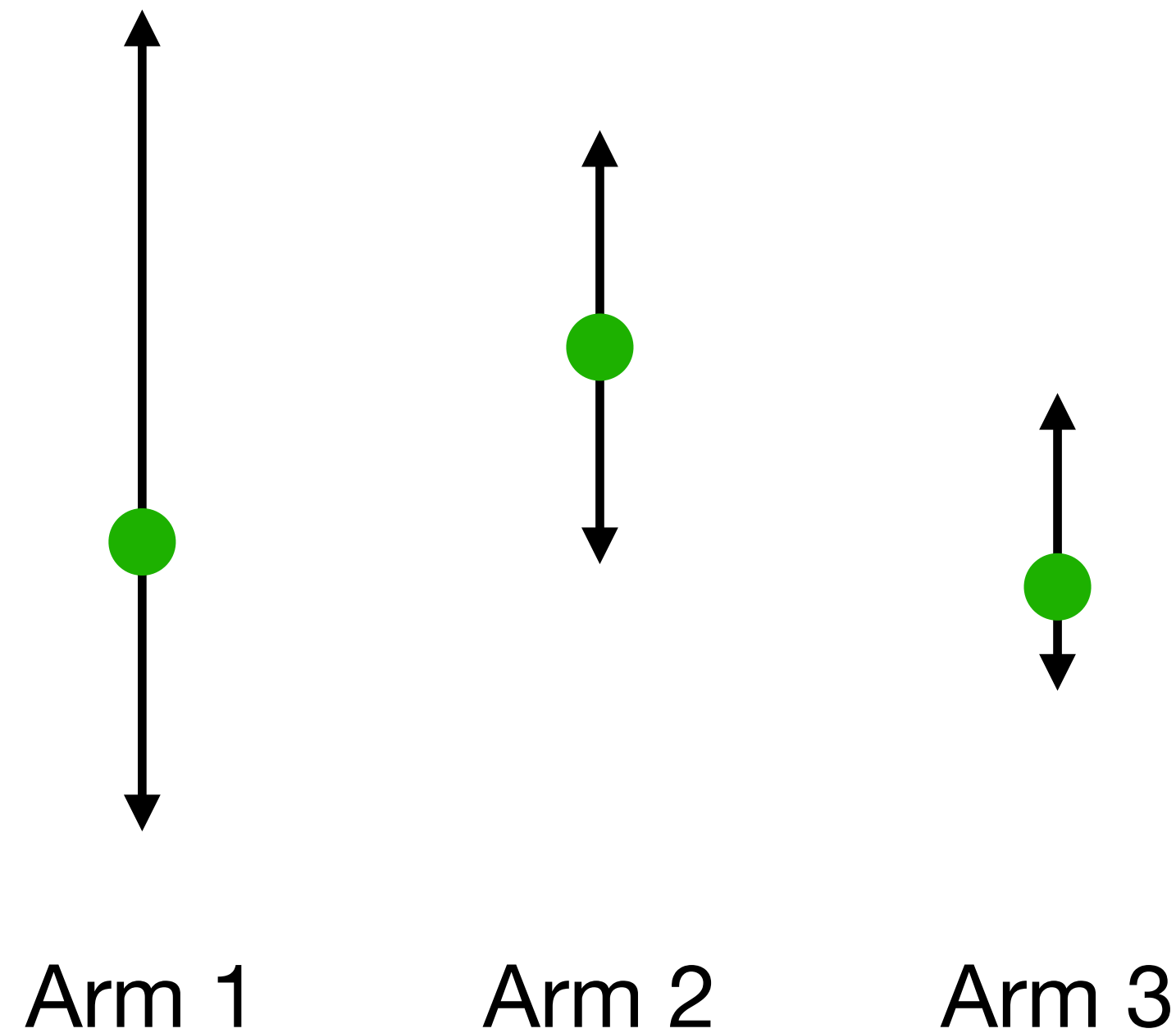


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$$\mathbb{E} \left[N\mu(a^\star) - \sum_{n=1}^N \mu(a^n) \right] \leq \tilde{O}(\sqrt{KN})$$

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$$\mathbb{E} \left[N\mu(a^\star) - \sum_{n=1}^N \mu(a^n) \right] \leq \tilde{O}(\sqrt{KN})$$

Key step in the proof:

$$\mu(a^\star) - \mu(a^n) \leq \hat{\mu}(a^n) + \sqrt{\frac{\ln(KN/\delta)}{N^n(a_n)}} - \mu(a^n)$$

Today: Efficient Learning in Finite Horizon tabular MDPs

Finite horizon episode (time-dependent) discrete MDP $\mathcal{M} = \{ \{r_h\}_{h=0}^{H-1}, \{P_h\}_{h=0}^H, H, \mu, S, A \}$

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EXPLORATION!

Why we need strategic exploration?

Initialization: s_0



Thrun '92

Length of chain is H

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Thrun '92

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Probability of random walk hitting reward 1 is $(1/3)^{-H}$

Learning Protocol

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1. Learner initializes a policy π^1

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2. At episode n , learner executes π^n :

$\{s_h^n, a_h^n, r_h^n\}_{h=0}^{H-1}$, with $a_h^n = \pi^n(s_h^n)$, $r_h^n = r(s_h^n, a_h^n)$, $s_{h+1}^n \sim P(\cdot | s_h^n, a_h^n)$

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Performance measure: REGRET

$$\mathbb{E} \left[\sum_{n=1}^N (V^* - V^{\pi^n}) \right] = \text{poly}(S, A, H) \sqrt{N}$$

Notations for Today

$$\mathbb{E}_{s' \sim P(\cdot | s, a)} [f(s')] := P(\cdot | s, a) \cdot f$$

$d_h^\pi(s, a)$: state-action distribution induced by π at time step h
(i.e., probability of π visiting (s, a) at time step h starting from s_0)

$$\pi = \{\pi_0, \dots, \pi_{H-1}\}$$

Outline for Today

1. Attempt 1: Treat MDP as a Multi-armed bandit problem and run UCB

1. Attempt 2: The Upper Confidence Bound Value Iteration Algorithm (UCB-VI)

2. UCB-VI's regret bound and the analysis

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Key lesson: shouldn't treat policies as independent arms — they do share information

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Inside iteration n :

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Optimistic planning with learned model: $\pi^n = \text{Value-Iter} \left(\{ \hat{P}_h^n, r_h + b_h^n \}_{h=1}^{H-1} \right)$

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Collect a new trajectory by executing π^n in the real world $\{P_h\}_{h=0}^{H-1}$ starting from s_0

UCBVI–Part 1: Model Estimation

Let us consider the **very beginning** of episode n :

$$\mathcal{D}_h^n = \{s_h^i, a_h^i, s_{h+1}^i\}_{i=1}^{n-1}, \forall h$$

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Estimate model $\widehat{P}_h^n(s' | s, a), \forall s, a, s', h$:

$$\widehat{P}_h^n(s' | s, a) = \frac{N_h^n(s, a, s')}{N_h^n(s, a)}$$

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UCBVI: Put All Together

For $n = 1 \rightarrow N$:

1. Set $N_h^n(s, a) = \sum_{i=1}^{n-1} \mathbf{1}\{(s_h^i, a_h^i) = (s, a)\}, \forall s, a, h$

2. Set $N_h^n(s, a, s') = \sum_{i=1}^{n-1} \mathbf{1}\{(s_h^i, a_h^i, s_{h+1}^i) = (s, a, s')\}, \forall s, a, a', h$

3. Estimate \hat{P}^n : $\hat{P}_h^n(s' | s, a) = \frac{N_h^n(s, a, s')}{N_h^n(s, a)}, \forall s, a, s', h$

4. Plan: $\pi^n = VI\left(\{\hat{P}_h^n, r_h + b_h^n\}_h\right)$, with $b_h^n(s, a) = cH \sqrt{\frac{\ln(SAHN/\delta)}{N_h^n(s, a)}}$

5. Execute π^n : $\{s_0^n, a_0^n, r_0^n, \dots, s_{H-1}^n, a_{H-1}^n, r_{H-1}^n, s_H^n\}$

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Theorem: UCBVI Regret Bound

$$\mathbb{E} \left[\text{Regret}_N \right] := \mathbb{E} \left[\sum_{n=1}^N (V^* - V^{\pi^n}) \right] \leq \tilde{O} \left(H^2 \sqrt{S^2 AN} \right)$$

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Remarks:

Note that we consider expected regret here (policy π^n is a random quantity).
High probability version is not hard to get (need to do a martingale argument)

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Dependency on H and S are suboptimal; but the **same** algorithm can achieve $H^2 \sqrt{SAN}$ in the leading term [Azar et.al 17 ICML, and the book Chapter 7]

Outline of Proof

Bonus $b_h^n(s, a)$ is related to $\left(\left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot V_{h+1}^\star \right)$

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Upper bound per-episode regret: $V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$

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Apply simulation lemma: $\widehat{V}_0^n(s_0) - V^{\pi^n}(s_0)$

1. Model Error using Hoeffding's inequality & Union Bound

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Given a fixed function $f : S \mapsto [0, H]$, w/ prob $1 - \delta$:

$$\left| \left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right)^\top f \right| \leq O\left(H \sqrt{\ln(SAHN/\delta) / N_h^n(s, a)}\right), \forall s, a, h, N$$

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Intuition:

1. Assume for some i , $s_h^i = s$, $a_h^i = a$, then $f(s_{h+1}^i)$ is an unbiased estimate of $\mathbb{E}_{s' \sim P_h(\cdot | s, a)} f(s')$

2. Note $\widehat{P}_h^n(\cdot | s, a) \cdot f = \frac{1}{N_h^n(s, a)} \sum_{i=1}^{n-1} \mathbf{1}[(s_h^i, a_h^i) = (s, a)] f(s_{h+1}^i)$

2. Proving Optimism via Induction

Lemma [Optimism]: $\widehat{V}_h^n(s) \geq V_h^\star(s), \forall n, h, s$

Recall Bonus-enhanced Value Iteration at episode n:

$$\widehat{V}_H^n(s) = 0, \quad \widehat{Q}_h^n(s, a) = \min \left\{ r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n, H \right\}$$
$$\widehat{V}_h^n(s) = \max_a \widehat{Q}_h^n(s, a), \quad \pi_h^n(s) = \arg \max_a \widehat{Q}_h^n(s, a), \forall s$$

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$$\widehat{Q}_h^n(s, a) - Q_h^\star(s, a) = r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n - r_h(s, a) - P_h(\cdot | s, a) \cdot V_{h+1}^\star$$

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$$\begin{aligned} \widehat{Q}_h^n(s, a) - Q_h^\star(s, a) &= r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n - r_h(s, a) - P_h(\cdot | s, a) \cdot V_{h+1}^\star \\ &\geq b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot V_{h+1}^\star - P_h(\cdot | s, a) \cdot V_{h+1}^\star \end{aligned}$$

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$$\geq b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot V_{h+1}^\star - P_h(\cdot | s, a) \cdot V_{h+1}^\star$$

$$= b_h^n(s, a) + \left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot V_{h+1}^\star$$

$$\geq b_h^n(s, a) - b_h^n(s, a) = 0, \quad \forall s, a$$

3. Upper Bounding Regret using Optimism

$$\text{per-episode regret} := V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$$

This is something
we can control!
And this is related
to our policy π^n

4. Upper bounding Regret via Simulation Lemma

$$\widehat{V}_H^n(s) = 0, \quad \widehat{Q}_h^n(s, a) = \min \left\{ r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n, H \right\}$$

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Lemma [Simulation lemma]:

$$\widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0) \leq \sum_{h=0}^{H-1} \mathbb{E}_{s, a \sim d_h^{\pi^n}} \left[b_h^n(s, a) + (\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a)) \cdot \widehat{V}_{h+1}^n \right]$$

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$$= \sum_{h=0}^{H-1} \mathbb{E}_{s, a \sim d_h^{\pi^n}} \left[b_h^n(s, a) + (\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a)) \cdot \widehat{V}_{h+1}^n \right]$$

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$$\text{per-episode regret} := V_0^\star(s_0) - V_0^{\pi_n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi_n}(s_0)$$

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$$\left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot \widehat{V}_{h+1}^n \leq \|P_h(\cdot | s, a) - \widehat{P}_h^n(\cdot | s, a)\|_1 \|\widehat{V}_{h+1}^n\|_\infty$$

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$$\leq H \|P_h(\cdot | s, a) - \widehat{P}_h^n(\cdot | s, a)\|_1 \leq H \sqrt{\frac{S \ln(SAHN/\delta)}{N_h^n(s, a)}}, \forall s, a, h, n, \text{ with prob } 1 - \delta$$

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$$\leq \sum_{h=0}^{H-1} \mathbb{E}_{s,a \sim d_h^{\pi_n}} \left[b_h^n(s, a) + H \sqrt{\frac{S \ln(SAHN/\delta)}{N_h^n(s, a)}} \right]$$

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$$\leq 2 \sum_{h=0}^{H-1} \mathbb{E}_{s,a \sim d_h^{\pi_n}} \left[H \sqrt{\frac{S \ln(SAHN/\delta)}{N_h^n(s, a)}} \right]$$

$$\left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot \widehat{V}_{h+1}^n \leq \|P_h(\cdot | s, a) - \widehat{P}_h^n(\cdot | s, a)\|_1 \|\widehat{V}_{h+1}^n\|_\infty$$

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$$\leq 2 \sum_{h=0}^{H-1} \mathbb{E}_{s,a \sim d_h^{\pi_n}} \left[H \sqrt{\frac{S \ln(SAHN/\delta)}{N_h^n(s, a)}} \right] = 2H \sqrt{S \ln(SAHN/\delta)} \sum_{h=0}^{H-1} \mathbb{E}_{s,a \sim d_h^{\pi_n}} \left[\sqrt{\frac{1}{N_h^n(s, a)}} \right]$$

$$\left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot \widehat{V}_{h+1}^n \leq \|P_h(\cdot | s, a) - \widehat{P}_h^n(\cdot | s, a)\|_1 \|\widehat{V}_{h+1}^n\|_\infty$$

$$\leq H \|P_h(\cdot | s, a) - \widehat{P}_h^n(\cdot | s, a)\|_1 \leq H \sqrt{\frac{S \ln(SAHN/\delta)}{N_h^n(s, a)}}, \forall s, a, h, n, \text{ with prob } 1 - \delta$$

5. Final Step

Remember we had two failure events for bounding transitions errors.

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$$\mathbb{E} [\text{Regret}_N] \leq 2H^2S\sqrt{AN \ln(SAHN/\delta)} + 2\delta NH \quad \text{Set } \delta = 1/(HN)$$

$$\leq 2H^2S\sqrt{AN \cdot \ln(SAH^2N^2)} = \tilde{O}\left(H^2S\sqrt{AN}\right)$$

High-level Idea: Exploration or Exploitation Tradeoff

Upper bound per-episode regret: $V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$

1. What if $\widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0) \leq \epsilon$?

Then π^n is close to π^\star , i.e., we are doing exploitation

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We collect data at steps where bonus is large or model is wrong, i.e., exploration