

Exploration in Linear MDPs

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CS 6789: Foundations of Reinforcement Learning

Recap: linear MDP definition

Finite horizon time-dependent episodic MDP $\mathcal{M} = \{S, A, H, \{r\}_h, \{P\}_h, s_0\}$

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Low-Rank
Decomposition:

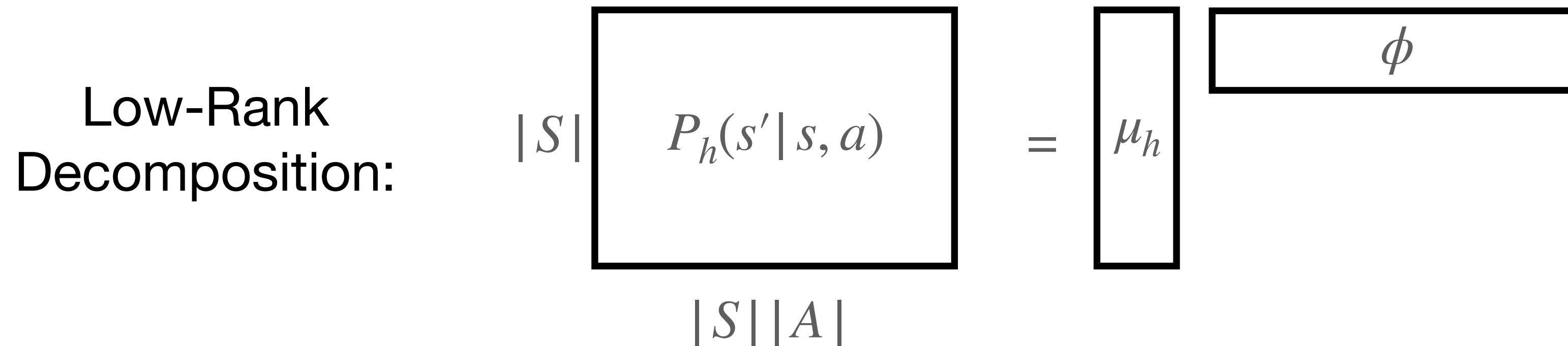
$$\begin{array}{c} |S| \\ \boxed{P_h(s'|s, a)} \\ |S||A| \end{array} = \begin{array}{c} \boxed{\mu_h} \\ \end{array} \begin{array}{c} \boxed{\phi} \end{array}$$

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$$P_h(s' | s, a) = \mu_h^\star(s') \cdot \phi(s, a), \quad \mu_h^\star \in S \mapsto \mathbb{R}^d, \phi \in S \times A \mapsto \mathbb{R}^d$$

$$r(s, a) = \theta_h^\star \cdot \phi(s, a), \quad \theta_h^\star \in \mathbb{R}^d$$



Recap:

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Given dataset $\{s_h^i, a_h^i, s_{h+1}^i\}_{i=1}^{n-1}$

Ridge Linear Regression:

$$\min_{\mu} \sum_{i=1}^{n-1} \|\mu \phi(s_h^i, a_h^i) - \delta(s_{h+1}^i)\|_2^2 + \lambda \|\mu\|_F^2$$

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$$\hat{\mu}_h^n = \sum_{i=1}^{n-1} \delta(s_{h+1}^i) \phi(s_h^i, a_h^i)^\top (\Lambda_h^n)^{-1}; \quad \hat{P}_h^n(\cdot | s, a) = \hat{\mu}_h^n \phi(s, a)$$

Today:

Regret bound for the UCBVI algorithm for Linear MDP and its proof sketch

Outline:

1. Model fitting and its guarantee $(\hat{P}(\cdot | s, a) - P(\cdot | s, a))^{\top} V$, for some fixed V
2. Covering argument to bound $(\hat{P}(\cdot | s, a) - P(\cdot | s, a))^{\top} V$, for ALL $V \in \mathcal{F}$
3. UCBVI revisit and its guarantee

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As in tabular-UCBVI and Generative Model, we care **average model error**:

Consider a fixed function $V : S \mapsto [0, H]$, we can bound:

$$\left| \left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot V \right|$$

1. Model Learning in Linear MDPs

Ridge Linear Regression:
$$\min_{\mu} \sum_{i=1}^{n-1} \|\mu \phi(s_h^i, a_h^i) - \delta(s_{h+1}^i)\|_2^2 + \|\mu\|_F^2$$

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Lemma [Model Average Error under a fixed V]:

Consider a fixed $V : S \rightarrow [0, H]$. With probability at least $1 - \delta$, for any s, a, h, n , we have:

$$\left| \left(\hat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot V \right| \leq \|\phi(s, a)\|_{(\Lambda_h^n)^{-1}} \times \left(2H \sqrt{\ln \frac{H \det(\Lambda_h^n)^{1/2} \det(\lambda I)^{-1/2}}{\delta}} + H \sqrt{\lambda d} \right)$$

1. Model Learning in Linear MDPs: proof

$$\hat{\mu}_h^n - \mu_h^\star = -\lambda \mu_h^\star (\Lambda_h^n)^{-1} + \sum_{i=1}^{n-1} \epsilon_h^i \phi(s_h^i, a_h^i)^\top (\Lambda_h^n)^{-1}$$

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$$= \mu_h^\star - \lambda \mu_h^\star (\Lambda_h^n)^{-1} + \sum_{i=1}^{n-1} \epsilon_h^i \phi(s_h^i, a_h^i)^\top (\Lambda_h^n)^{-1}$$

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$$\mathbb{E} [(\epsilon_h^i)^\top V | \mathcal{H}_{i,h}] = 0, \quad |(\epsilon_h^i)^\top V| \leq \|\epsilon_h^i\|_1 \|V\|_\infty \leq 2H$$

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$$= \|\phi(s, a)\|_{(\Lambda_h^n)^{-1}} \left\| \sum_{i=1}^{n-1} \phi(s_h^i, a_h^i) ((\epsilon_h^i)^\top V) \right\|_{(\Lambda_h^n)^{-1}} \leq \|\phi(s, a)^\top\|_{(\Lambda_h^n)^{-1}} \times 2H \sqrt{\ln \frac{\det(\Lambda_h^n)^{1/2} \det(\lambda I)^{-1/2}}{\delta}}$$

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1. Model Learning in Linear MDPs

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With prob $1 - \delta$, $\forall n$

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1. Model Learning in Linear MDPs

Lemma [Model Average Error under a fixed V]:

Consider a fixed $V : S \rightarrow [0, H]$. With probability at least $1 - \delta$, for all s, a, n, h , we have:

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$$\begin{aligned} \left| \left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot V \right| &\leq \|\phi(s, a)\|_{(\Lambda_h^n)^{-1}} \left(2H \sqrt{d \ln \left(\frac{NH}{\lambda} + 1 \right)} + \ln \left(\frac{1}{\delta} \right) + H \sqrt{\lambda d} \right) \\ &= \widetilde{O} \left(H \sqrt{d} + H \sqrt{\ln(1/\delta)} \right) \|\phi(s, a)\|_{(\Lambda_h^n)^{-1}} \end{aligned}$$

1. Model learning: summary

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Q: Can we get a uniform convergence argument for a function class \mathcal{F} ?

Outline:



1. Model fitting and its guarantee $(\hat{P}(\cdot | s, a) - P(\cdot | s, a))^{\top} V$, for some fixed V

2. Covering argument to bound $(\hat{P}(\cdot | s, a) - P(\cdot | s, a))^{\top} V$, for ALL $V \in \mathcal{F}$

3. UCBVI revisit and its guarantee

Detour: Covering Number

Consider the ball $\Theta = \{\theta : \theta \in \mathbb{R}^d, \|\theta\|_2 \leq R\}$.

Denote ϵ -**Net** as a subset $\mathcal{N}_\epsilon \subseteq \Theta$, such that $\forall \theta \in \Theta$:

$$\exists \theta' \in \mathcal{N}_\epsilon, \text{ s.t. } \|\theta' - \theta\|_2 \leq \epsilon.$$

Denote ϵ -**cover** as the smallest \mathcal{N}_ϵ

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Then (ϵ/L) -Net on Θ gives us an ϵ -Net on \mathcal{F} with $d(f_{\theta_1}, f_{\theta_2}) := \|f_{\theta_1} - f_{\theta_2}\|_\infty$

Detour: Covering Number and An Example

Consider a specific parameterization $\theta = (w, \beta, \Lambda)$,
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Denote $\mathcal{F} = \{f_{w, \beta, \Lambda} : \|w\|_2 \leq L, \beta \in [0, B], \sigma_{\min}(\Lambda) \geq \lambda\}$, **what's the covering number of \mathcal{F} under ℓ_∞**

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Lemma: Denote $\mathcal{F} = \{f_{w,\beta,\Lambda} : \|w\|_2 \leq L, \beta \in [0, B], \sigma_{\min}(\Lambda) \geq \lambda\}$,
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Key step in the proof:

$$\left| f_\theta(s) - f_{\hat{\theta}}(s) \right| \leq \|w - \hat{w}\|_2 + |\beta - \hat{\beta}|/\sqrt{\lambda} + B\sqrt{\|\Lambda^{-1} - \hat{\Lambda}^{-1}\|_F}$$

Detour: Uniform Convergence

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Lemma [uniform convergence]: With probability at least $1 - \delta$, for all s, a, h, n , and **ALL** $f \in \mathcal{F}$:

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Proof sketch: the model error we had for a fixed $V + \epsilon$ -Net argument
(Same high level steps as the ones we used for HW1's last question)

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This will be our bonus term

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Summary of Covering Argument

Covering allows us to build a uniform convergence result (i.e., $\forall f \in \mathcal{F}$)
over a infinite hypothesis class
(Intuitively, log of covering number scales w.r.t to the # of parameters)

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3. UCBVI revisit and its guarantee

Algorithm: UCBVI in Linear MDPs

At the beginning of iteration n :

1. Learn transition model $\{\hat{P}_h^n\}_{h=0}^{H-1}$ from all previous data via Ridge linear regression

$$\# \text{ comment: } \min_{\mu} \sum_{i=1}^{n-1} \|\mu \phi(s_h^i, a_h^i) - \delta(s_{h+1}^i)\|_2^2 + \lambda \|\mu\|_F^2$$

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4. Execute π^{n+1} for H steps

Regret bound for UCBVI in linear MDP

$$\mathbb{E} \left[\sum_{n=1}^N (V^{\star} - V^{\pi^n}) \right] \leq \widetilde{O}(H^2 d^{1.5} \sqrt{N})$$

No S or A polynomial dependence!

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2. Value Iteration in the Learned Model w/ Reward Bonus

$$\pi^{n+1} = \text{Value-Iter} \left(\{ \widehat{P}^n \}_h, \{ r_h + b_h^n \} \right)$$

$$\widehat{V}_H^n(s) = 0, \forall s,$$

$$\widehat{Q}_h^n(s, a) = r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n$$

$$= \theta_h^\star \cdot \phi(s, a) + \beta \sqrt{\phi(s, a)^\top (\Lambda_h^n)^{-1} \phi(s, a)} + (\widehat{\mu}_h^n \phi(s, a))^\top \widehat{V}_{h+1}^n$$

$$= \beta \sqrt{\phi(s, a)^\top (\Lambda_h^n)^{-1} \phi(s, a)} + \left(\theta_h^\star + (\widehat{\mu}_h^n)^\top \widehat{V}_{h+1}^n(s') \right)^\top \phi(s, a)$$

$$= \beta \sqrt{\phi(s, a)^\top (\Lambda_h^n)^{-1} \phi(s, a)} + \phi(s, a)^\top \widehat{w}_h^n$$

$$\widehat{V}_h^n(s) = \min \left\{ \max_a \left(\phi(s, a)^\top \widehat{w}_h^n + \beta \sqrt{\phi(s, a)^\top (\Lambda_h^n)^{-1} \phi(s, a)} \right), H \right\}, \quad \pi_h^n(s) = \arg \max_a \widehat{Q}_h^n(s, a)$$

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Lemma [Optimism]: with high probability, for all n, h, s :

$$\widehat{V}_h^n(s) \geq V_h^*(s)$$

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$$\geq 0$$

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Conditioned on history up to the end of episode $n-1$:

$$V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$$

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$$\mathbb{E} \left[\sum_{n=1}^N (V_0^*(s_0) - V_0^{\pi^n}(s_0)) \right] = \mathbb{E} \left[\mathbf{1}[\text{good event holds}] \sum_{n=1}^N (V_0^*(s_0) - V_0^{\pi^n}(s_0)) \right] + \mathbb{E} \left[\mathbf{1}[\text{good event doesn't hold}] \sum_{n=1}^N (V_0^*(s_0) - V_0^{\pi^n}(s_0)) \right]$$

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&\lesssim \widetilde{O}(H^2 d^{1.5} \sqrt{N})
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W/ optimism (thanks to bonus which offsets errors in estimated models):

$$V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0) \lesssim \sum_{h=0}^{H-1} \mathbb{E}_{s_h, a_h \sim d_h^{\pi^n}} [b_h^n(s_h, a_h)]$$

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Thus, when our policy is suboptimal, i.e., $V_0^\star(s_0) - V_0^{\pi^n}(s_0) \geq \epsilon$

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Since we live in a d -dim space, eventually we will explore all possible directions.