

Exploration in Tabular MDPs

CS 6789: Foundations of Reinforcement Learning

Recap: UCBVI

For $n = 1 \rightarrow N$:

1. Set $N_h^n(s, a) = \sum_{i=1}^{n-1} \mathbf{1}\{(s_h^i, a_h^i) = (s, a)\}, \forall s, a, h$

2. Set $N_h^n(s, a, s') = \sum_{i=1}^{n-1} \mathbf{1}\{(s_h^i, a_h^i, s_{h+1}^i) = (s, a, s')\}, \forall s, a, a', h$

3. Estimate \hat{P}^n : $\hat{P}_h^n(s' | s, a) = \frac{N_h^n(s, a, s')}{N_h^n(s, a)}, \forall s, a, s', h$

4. Plan: $\pi^n = VI\left(\{\hat{P}_h^n, r_h + b_h^n\}_h\right)$, with $b_h^n(s, a) = cH \sqrt{\frac{\ln(SAHN/\delta)}{N_h^n(s, a)}}$

5. Execute π^n : $\{s_0^n, a_0^n, r_0^n, \dots, s_{H-1}^n, a_{H-1}^n, r_{H-1}^n, s_H^n\}$

Outline of Proof

Bonus $b_h^n(s, a)$ is related to $\left(\left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot V_{h+1}^\star \right)$

Outline of Proof

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Upper bound per-episode regret: $V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$

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Apply simulation lemma: $\widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$

1. Model Error using Hoeffding's inequality & Union Bound

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Given a fixed function $f : S \mapsto [0, H]$, w/ prob $1 - \delta$:

$$\left| \left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right)^\top f \right| \leq O\left(H \sqrt{\ln(SAHN/\delta) / N_h^n(s, a)}\right), \forall s, a, h, N$$

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2. Note $\widehat{P}_h^n(\cdot | s, a) \cdot f = \frac{1}{N_h^n(s, a)} \sum_{i=1}^{n-1} \mathbf{1}[(s_h^i, a_h^i) = (s, a)] f(s_{h+1}^i)$

2. Proving Optimism via Induction

Lemma [Optimism]: $\widehat{V}_h^n(s) \geq V_h^\star(s), \forall n, h, s$

Recall Bonus-enhanced Value Iteration at episode n:

$$\widehat{V}_H^n(s) = 0, \quad \widehat{Q}_h^n(s, a) = \min \left\{ r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n, H \right\}$$
$$\widehat{V}_h^n(s) = \max_a \widehat{Q}_h^n(s, a), \quad \pi_h^n(s) = \arg \max_a \widehat{Q}_h^n(s, a), \forall s$$

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$$\widehat{Q}_h^n(s, a) - Q_h^\star(s, a) = r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n - r_h(s, a) - P_h(\cdot | s, a) \cdot V_{h+1}^\star$$

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$$\begin{aligned} \widehat{Q}_h^n(s, a) - Q_h^\star(s, a) &= r_h(s, a) + b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot \widehat{V}_{h+1}^n - r_h(s, a) - P_h(\cdot | s, a) \cdot V_{h+1}^\star \\ &\geq b_h^n(s, a) + \widehat{P}_h^n(\cdot | s, a) \cdot V_{h+1}^\star - P_h(\cdot | s, a) \cdot V_{h+1}^\star \end{aligned}$$

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$$\geq b_h^n(s, a) - b_h^n(s, a) = 0, \quad \forall s, a$$

3. Upper Bounding Regret using Optimism

$$\text{per-episode regret} := V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$$

This is something
we can control!
And this is related
to our policy π^n

4. Upper bounding Regret via Simulation Lemma

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$$\leq r_0(s_0, \pi^n(s_0)) + b_h^n(s_0, \pi^n(s_0)) + \widehat{P}_0^n(\cdot | s_0, \pi^n(s_0)) \cdot \widehat{V}_1^n - r_0(s_0, \pi^n(s_0)) - P_0(\cdot | s_0, \pi^n(s_0)) \cdot V_1^{\pi^n}$$

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per-episode regret $:= V_0^\star(s_0) - V_0^{\pi_n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi_n}(s_0)$ But \widehat{V}_h^n is data-dependent
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$$\leq 2 \sum_{h=0}^{H-1} \mathbb{E}_{s,a \sim d_h^{\pi_n}} \left[H \sqrt{\frac{S \ln(SAHN/\delta)}{N_h^n(s, a)}} \right] = 2H \sqrt{S \ln(SAHN/\delta)} \sum_{h=0}^{H-1} \mathbb{E}_{s,a \sim d_h^{\pi_n}} \left[\sqrt{\frac{1}{N_h^n(s, a)}} \right]$$

$$\left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot \widehat{V}_{h+1}^n \leq \|P_h(\cdot | s, a) - \widehat{P}_h^n(\cdot | s, a)\|_1 \|\widehat{V}_{h+1}^n\|_\infty$$

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$$\leq 2H^2S\sqrt{AN \cdot \ln(SAH^2N^2)} = \tilde{O}\left(H^2S\sqrt{AN}\right)$$

High-level Idea: Exploration or Exploitation Tradeoff

Upper bound per-episode regret: $V_0^\star(s_0) - V_0^{\pi^n}(s_0) \leq \widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0)$

1. What if $\widehat{V}_0^n(s_0) - V_0^{\pi^n}(s_0) \leq \epsilon$?

Then π^n is close to π^\star , i.e., we are doing exploitation

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We collect data at steps where bonus is large or model is wrong, i.e., exploration

Summary of the Proof of UCB-VI

Bonus $b^n(s, a)$ is related to $\left(\left(\widehat{P}_h^n(\cdot | s, a) - P_h(\cdot | s, a) \right) \cdot V_{h+1}^\star \right)$

Prove Optimism via Induction: it allows us to focus π^n rather than π^\star which is unknown)

Bound per-episode regret via Simulation Lemma (Perf diff of π^n under \widehat{P}^n & P)

Bounding conf-term along traces: $\sum_n \sum_h \sqrt{\frac{1}{N_h^n(s_h^n, a_h^n)}}$